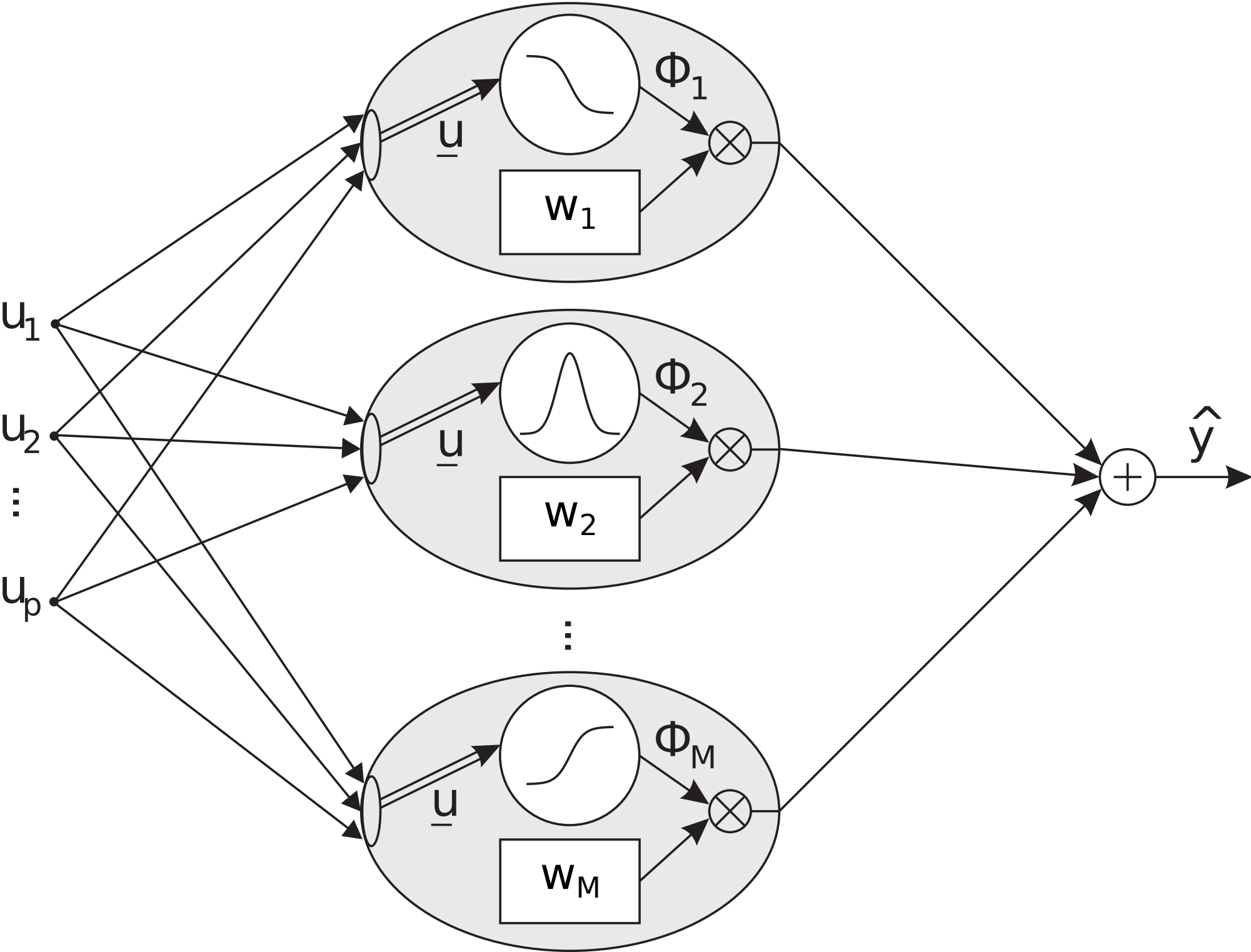
u_1
u_2
u_p
Φ_1
$\underline{u}$
w_1
Φ_2
$\underline{u}$
w_2
Φ_M
$\underline{u}$
w_M
$\hat{y}$