



Analysis of the temperature development within a brake disk P. Falk, J. Schulte, M. Dittmann, C. Hesch and C. P. Fritzen

Motivation

- Determination of the peak temperature and the core temperature
- Distribution of thermal energy between the brake disc and brake pad

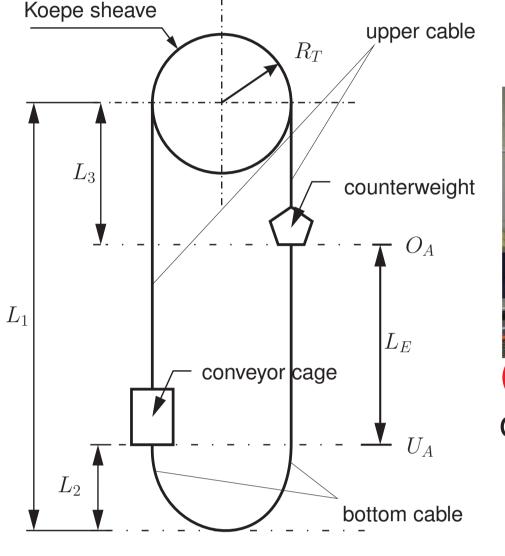
Measurement

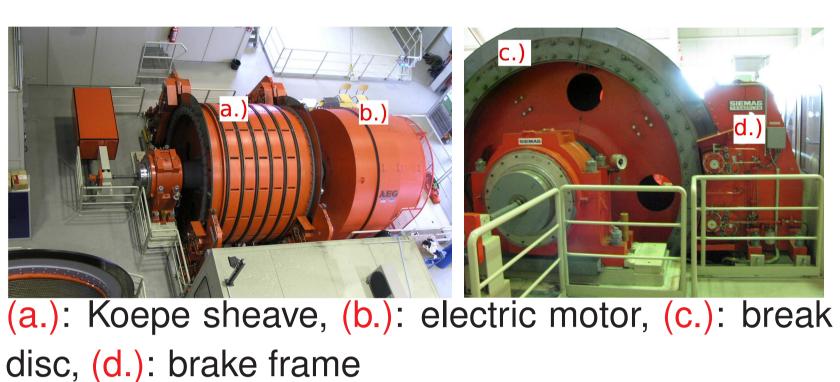
Measurement setup

room thermometer

Determination of the heat conduction and material parameters

Construction of the conveyor system





Derivation

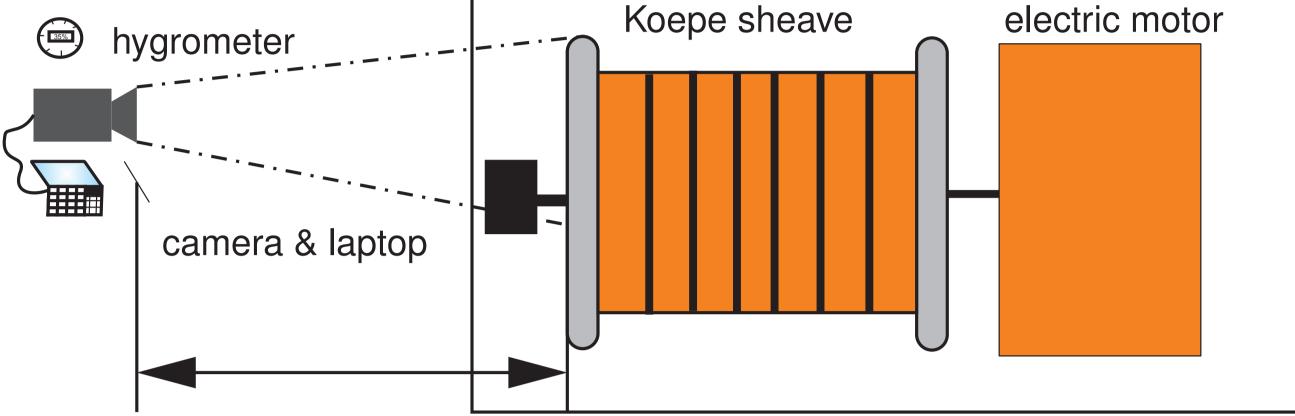
First law of thermodynamics

 $Q + P = \frac{d}{dt}[T + E]$

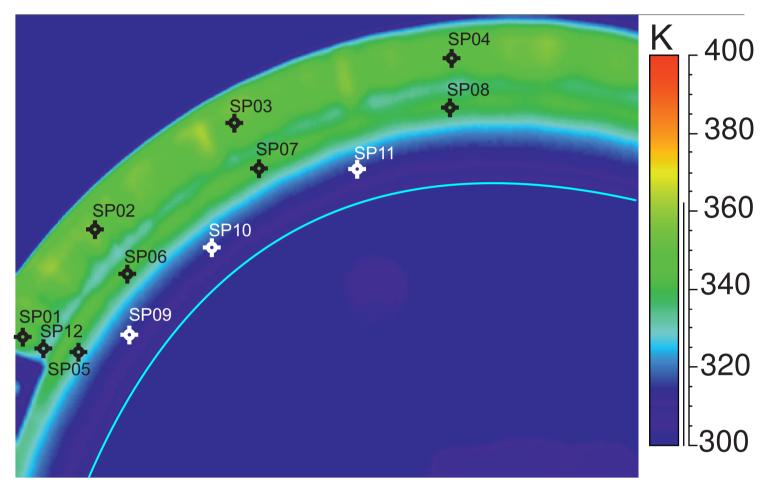
Heat energy is obtained from dissipated mechanicl energy

$$Q_{fric} = -P_{fric}$$

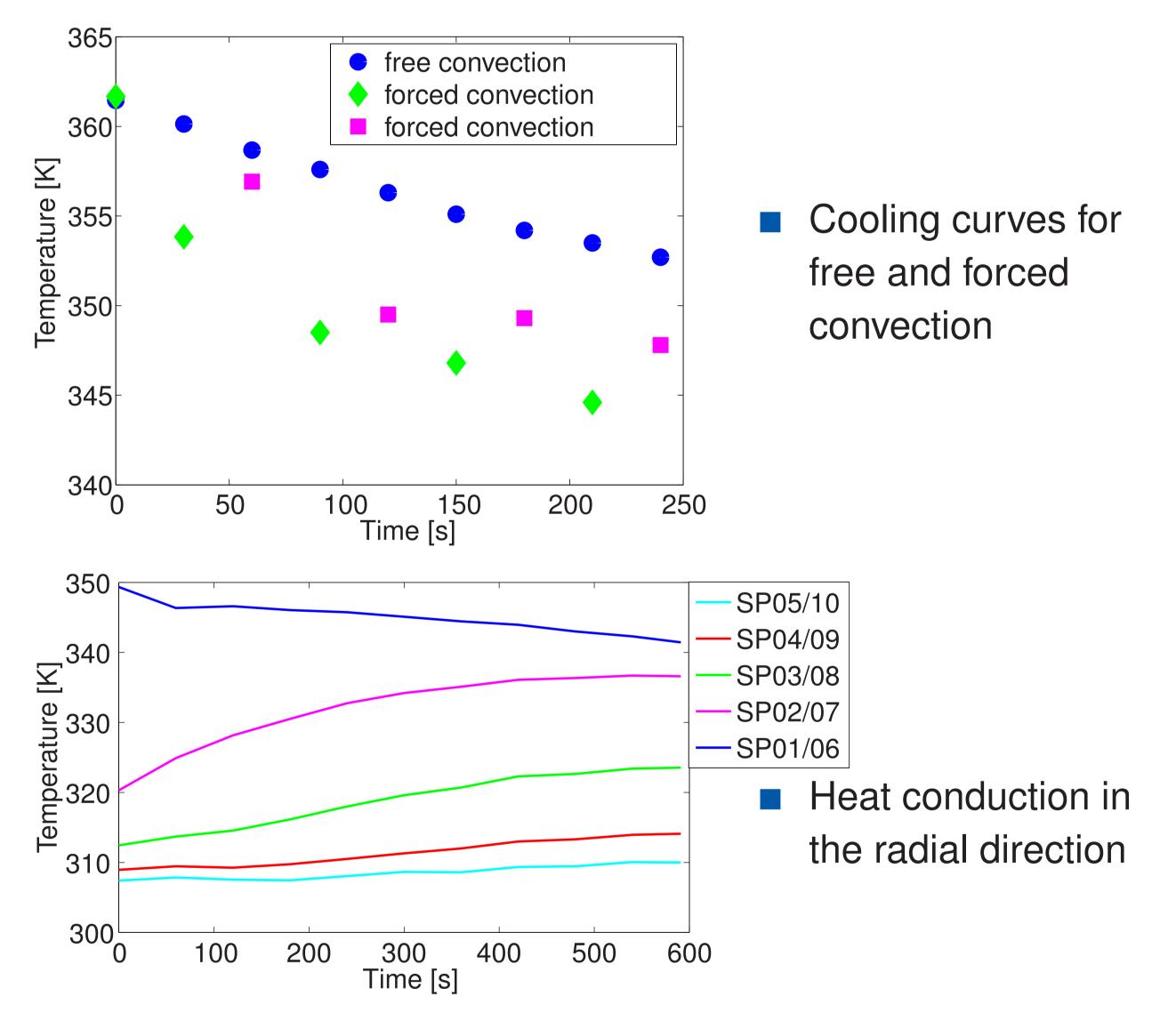
Thermal balance equation (strong formulation)



3,5 m



Measurement results



Thermographic camera from FLIR Evaluation software Researcher Pro 2.10

$$c_p \rho \theta - k \Delta \theta = 0$$

Weak formulation $\delta\theta c_p \rho \dot{\theta} dV + \int$ $k \nabla(\delta \theta) \nabla \theta \mathrm{d} V$ (1) J_{Ω_0} $-\int_{\partial\Omega_N} \delta\theta \, h \, \mathrm{d}A - \int_{\partial\Omega_R} \delta\theta \, \alpha \left(T_{flu} - \theta\right) \mathrm{d}A = 0$

Discretization (spatial, semi-discrete)

$$\mathbf{C}\,\dot{\mathbf{\Theta}} + \mathbf{K}\,\mathbf{\Theta} - \mathbf{f} = \mathbf{0}$$

• Discretization in time:
$$\dot{\theta} = (\theta_{n+1} - \theta_n)/\Delta t$$

$$\left[\frac{1}{\Delta t}\mathbf{C} + \mathbf{K}\right] \mathbf{\Theta}_{n+1} - \left[\mathbf{f}(t_{n+1}) + \frac{1}{\Delta t}\mathbf{C}\mathbf{\Theta}_n\right] = \mathbf{0}$$

Boundary conditions

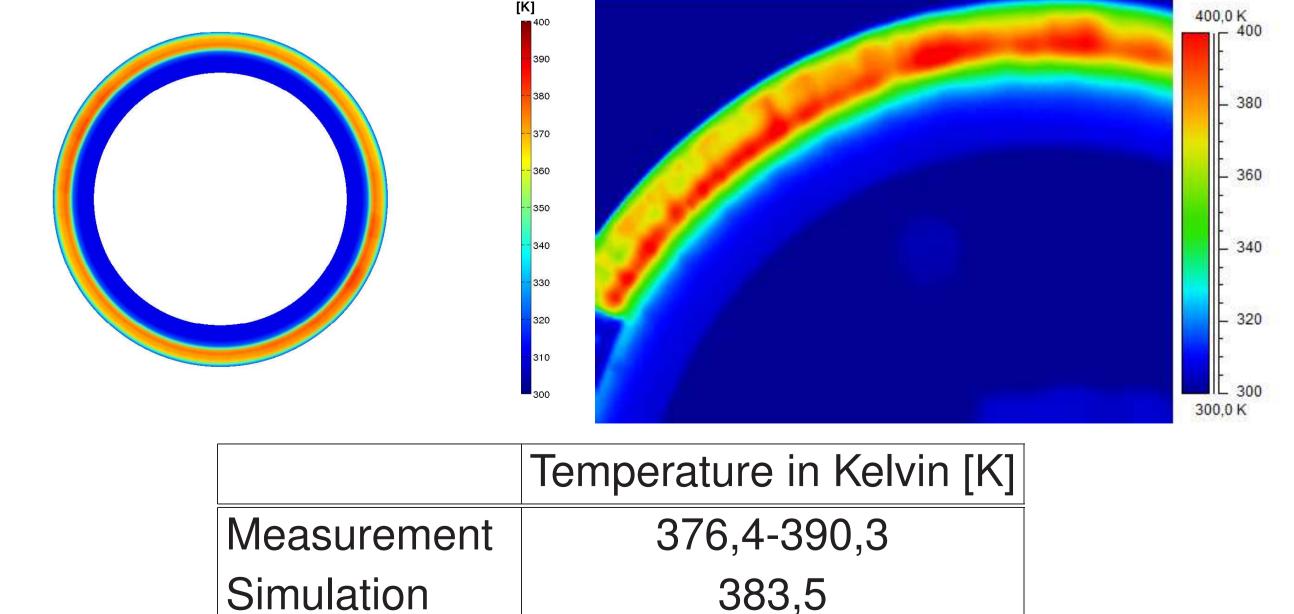
Overfall heat flux on boundary

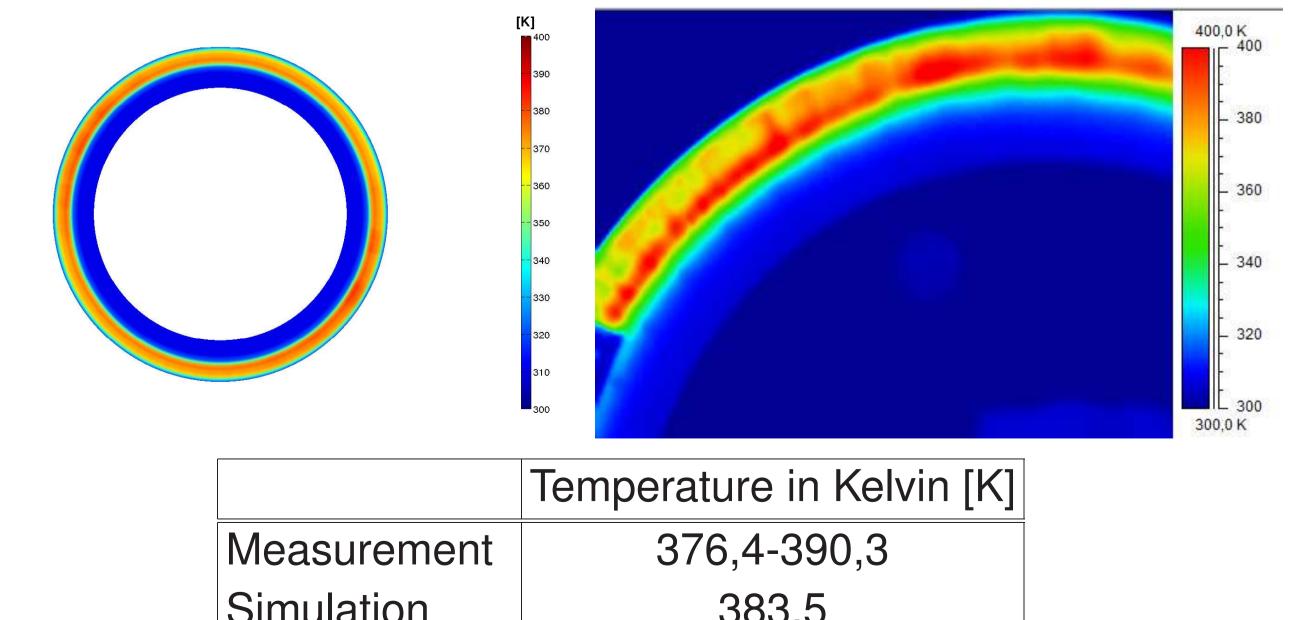
$$Q = \gamma Q_{fric} + Q_{con}$$

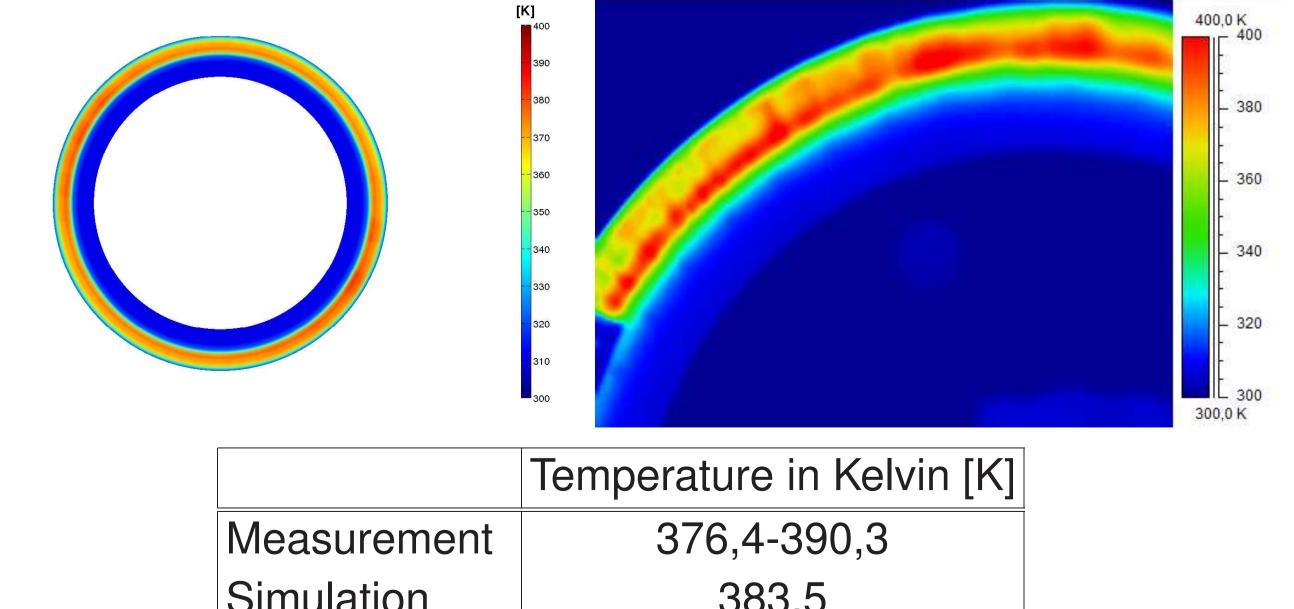
Conduction Convection Radiation

Fluid

Simulation







Neumann boundary

 \bullet h is introduced across the surface of the brake pads

$$\gamma Q_{fric} = \int_{\partial \Omega_N} h \, \mathrm{d}A$$

Robin boundary

Heat transfer $Q_{con} = \int_{\partial \Omega_R} \alpha \left(T_{flu} - \Theta \right) dA$ Forced convection $\alpha = \frac{Nu(Re, Pr)k}{r} \qquad \qquad \alpha = \frac{Nu(Gr, Pr)k}{r}$

University of Siegen **Chair of Computational Mechanics**

Prof. Dr.-Ing. habil. C. Hesch